




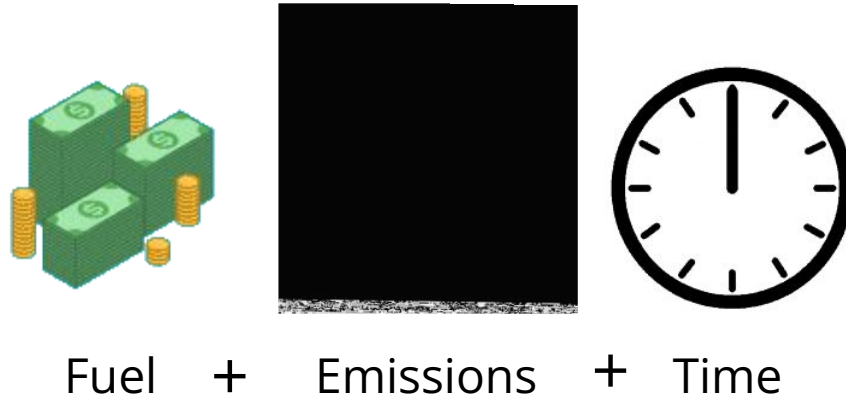
iValet Initial Proposal

Members: Faiza Yousuf, Kelin Yu,
Wei Xiong Toh, Yunchu Feng



Parking Problem

- Drivers spend 17h per year on average searching for parking



\$345/year

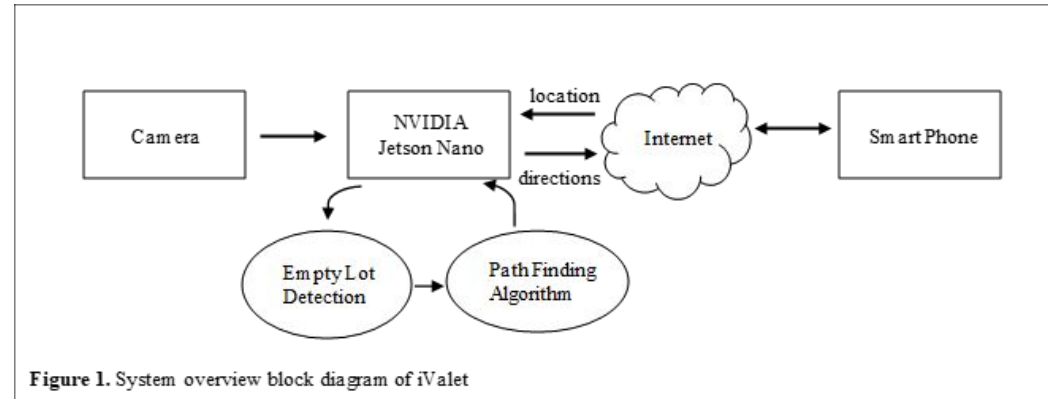
Objective

- Address the difficulty in finding empty parking spaces
- User-friendly application
- Directs drivers to next available parking spot



Components

- Camera
 - e-CAM24_CUNX - Color Global shutter Camera
 - e-CAM50_CUNX - 5.0 MP NVIDIA® Jetson Xavier™ NX/NVIDIA® Jetson Nano™ Camera
 - 13 MP, 30 fps Color Camera Rolling Shutter
- Processor
 - Nvidia Jetson Nano Developer Kit
- Site hosting
 - Netlify



Camera Options



e-CAM24_CUNX - Color Global shutter Camera

Frame Rate: 65-120 fps

Operating Voltage: 3.3V +/- 5%

Power Consumption:
0.66W-0.92W

Weight: 21g



e-CAM50_CUNX - 5.0 MP NVIDIA® Jetson Xavier™ NX/NVIDIA® Jetson Nano™ Camera

Frame Rate: 28-100 fps

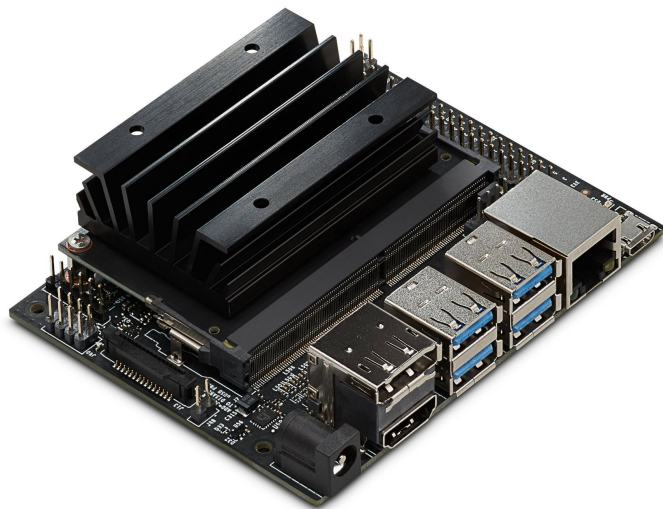
Operating Voltage: 3.3V +/- 5%

Power Consumption:
0.95W-1.62W

Weight: 17.5g

Nvidia Jetson Nano Developer Kit

- Designed to be a portable AI and machine learning computer
 - Main storage: microSD card slot
 - 40 pin expansion header
 - 5V power through Micro-USB or DC Barrel Jack
 - Gigabit Ethernet Port
 - 4 USB 3.0 ports
 - HDMI Output
 - Device Mode through Micro-USB
 - DisplayPort Connector
 - MIPI CSI-2 camera connectors



Overall Budget

e-CAM24_CUNX Global shutter Camera	Camera	\$149.00
e-CAM50_CUNX 5.0 MP Camera	Camera	\$99.00
NVIDIA Jetson Nano Developer Kit	Computation/Processing	\$99.00
	Total	\$347.00

Design Concept

- Algorithm

- Problems:

- Process parking lots image

- Handled by OpenCV (open-source library for image processing and machine learning)

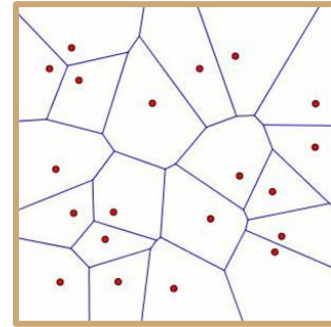
- Map available spaces

- Use Voronoi diagrams to divide parking lots into sections
- Create flags to differentiate between taken, and soon to be taken, and filled spaces

- Help users find a spot

- Data from the Voronoi diagram will be used to update the pathfinding algorithm
- Path to each space will be calculated using the A* method
 - Most valuable when finding the optimal route between 2 points
 - Typically deployed when routing to a specific location

Voronoi Diagram
Source: American
Mathematical Society



Design Concept

- User Interface
 - A webpage that will be accessed via QR code

Home Screen

Car ID info

Model: ▼

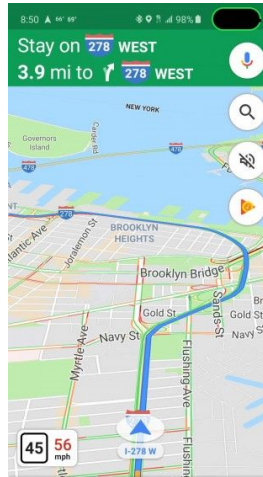
Color: ▼

License Plate:

Find a Spot

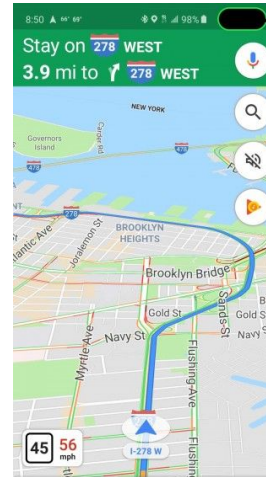
Find where
you parked

Navigate to Slot

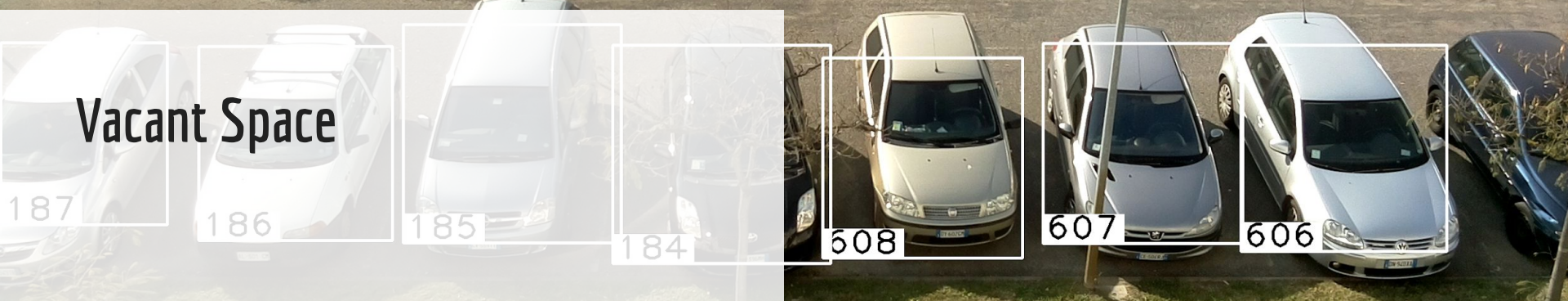


Will you be
parked here?

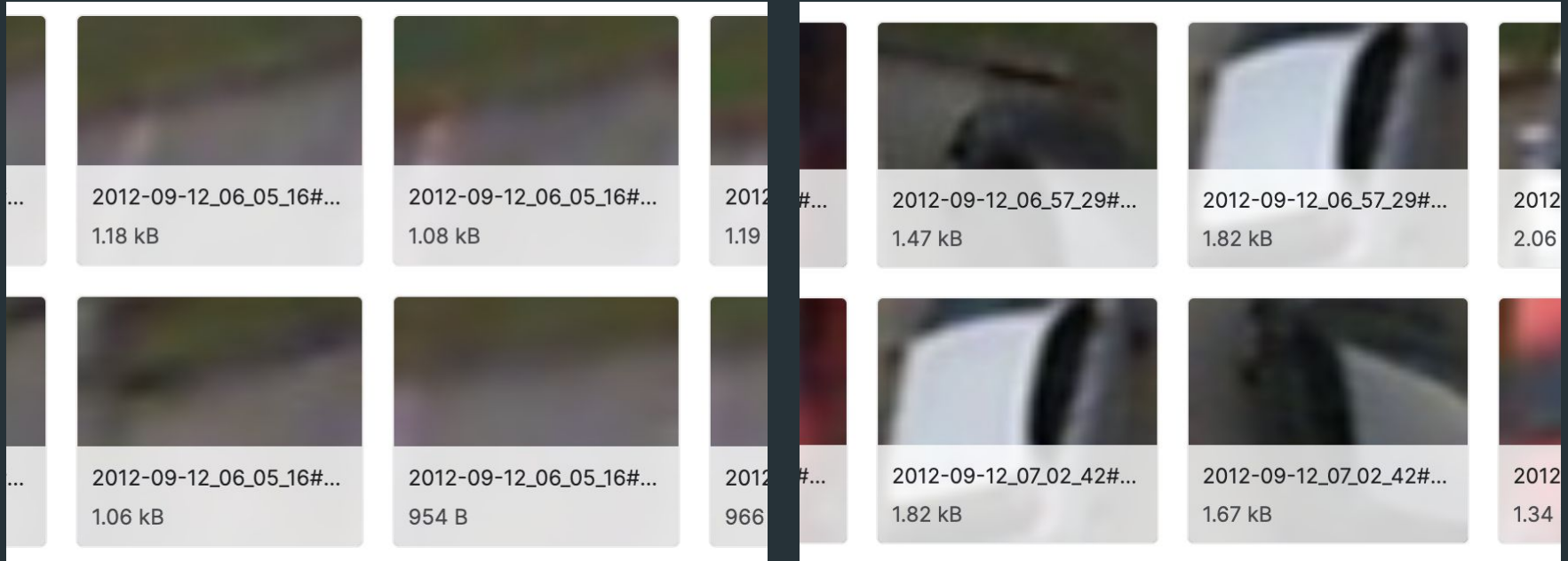
Navigate Back



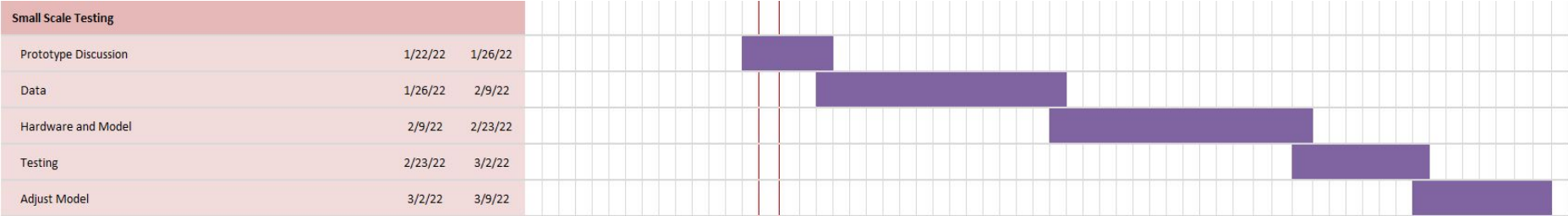
Thank you!



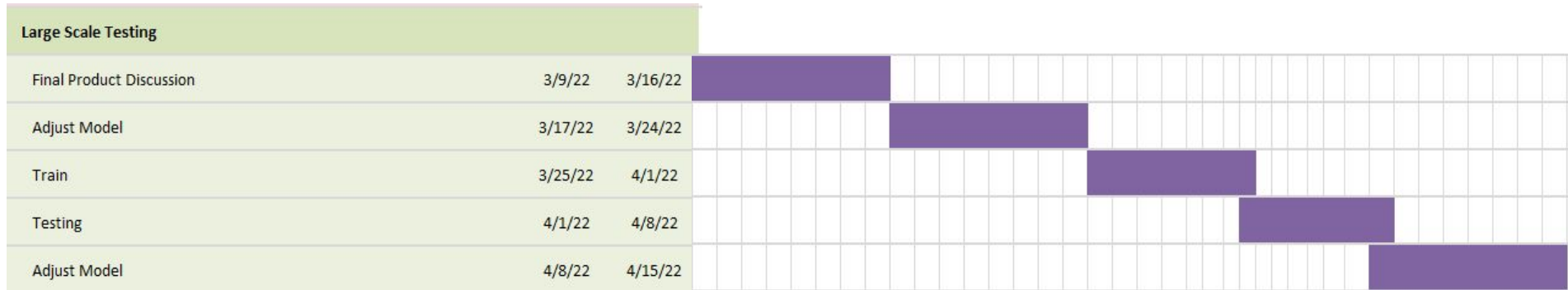
Data - Kaggle Data Base



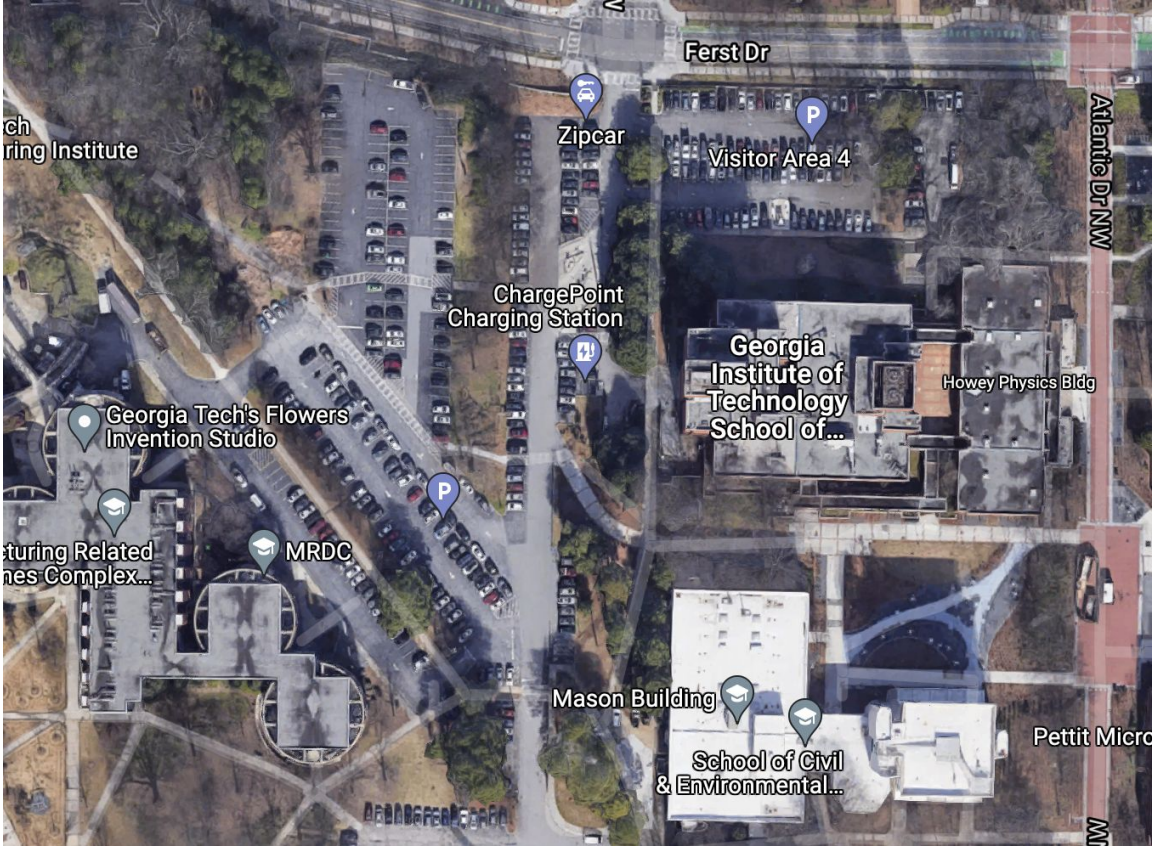
Design and Initial Testing Schedule



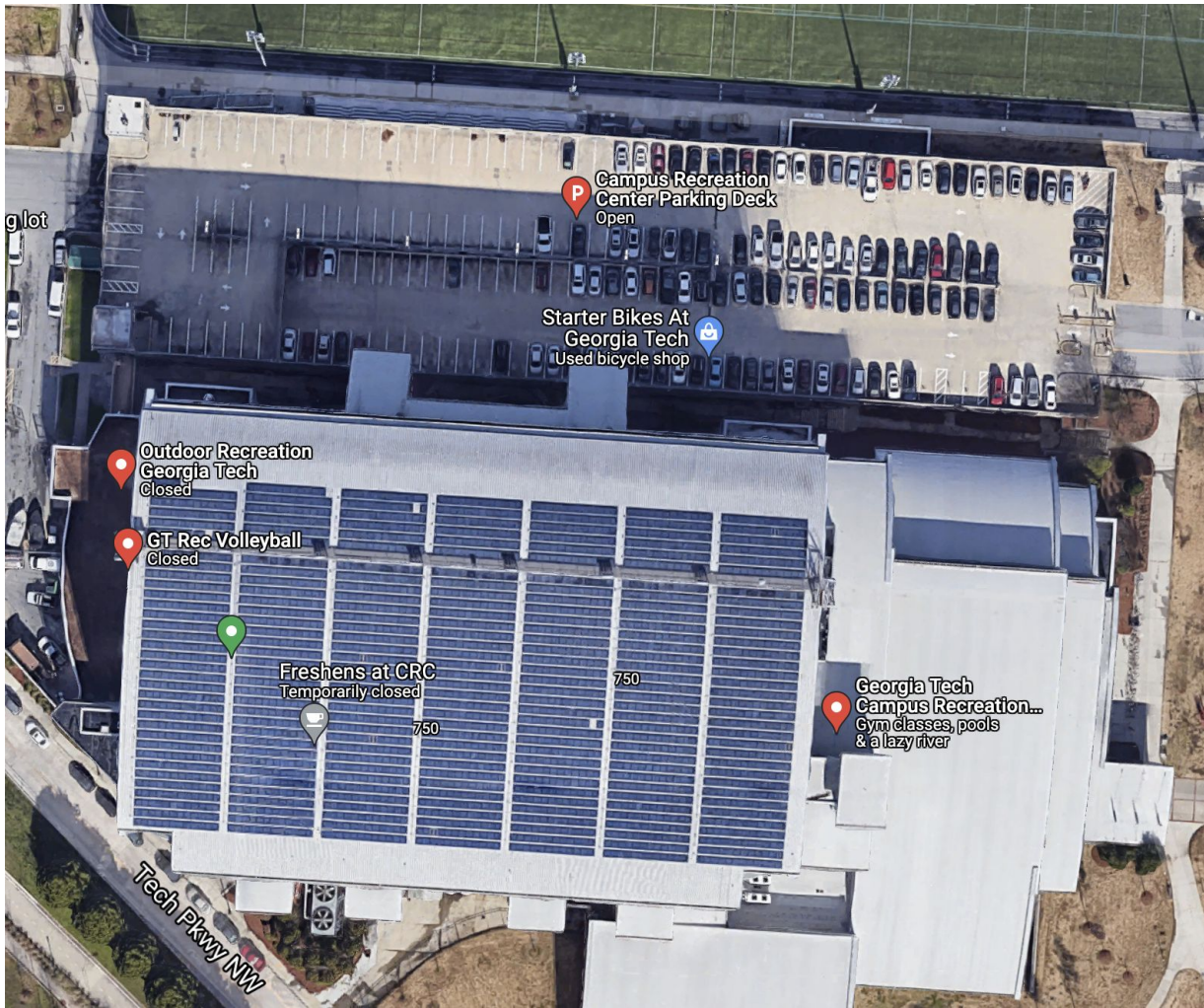
Testing and Redesign Schedule



Testing Sites







g lot

**Campus Recreation
Center Parking Deck**
Open

**Starter Bikes At
Georgia Tech**
Used bicycle shop

**Outdoor Recreation
Georgia Tech**
Closed

GT Rec Volleyball
Closed

Freshens at CRC
Temporarily closed

**Georgia Tech
Campus Recreation...**
Gym classes, pools
& a lazy river

Tech Pkwy NW

750

750

Team Member Assignments

- Group Leader/Financial Manager: Wei Xiong
- Webmaster: Faiza Yousuf
- Hardware Technical Lead: Kelin
- Software Technical Lead: Yunchu Feng