Acoustic Source Localization

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Introduction

- Objective
 - To identify the location of a sound source in a given area
- Motivation
 - We would like to make an alternated detection method that offer an alternative approach to video detection.
- Background
 - Different Methods
 - Time of arrival
 - Time difference of arrival
 - Receiver signal strength





Raspberry Pi and Matrix Setup

- Two functioning Matrix modules each with a Pi
- Pi's can be 3 or 4
 - Buster OS
 - Matrix HAL Library
- Localization.py
 - Runs recording executable via subprocess
 - Converts .raw files to .wav
 - Begins localization algorithm

Design Specification

| Parameters | Specifications |
|---------------------|---|
| Audio Specification | 8-96 kHz |
| Bit Depth | Signed 16 bits |
| Operation Range | 20 meters |
| Cost | Below \$200 |
| Angle Accuracy | Average difference within 3 degrees |
| Distance Accuracy | Average difference within 30 centimeters |
| Processing Delay | Average processing delay within half second |

Design Approach-Algorithm



Angle Calculation

1. Uses Pesudo Far-field Assumption

2. Average over multiple angle estimation

3. Uses an outlier filter to enhance stability

4. Uses decision-feedback to perform error correction



Comparison to other methods

- ODAS (Open Embedded Audio System)
- Gillete-Silverman Algorithm
- Far-field Algorithm
- Closed-form approach
- MUSIC (Multiple Signal Classification)

Tracking and Multi-source

- ODAS' probabilistic approach
- Prediction->Likelihood (Prior and Posterior probability)->add and remove sources-> update.

Project Demonstration

- Video of working project
- Will provide overview of GUI
- Will test speech/acoustic signals
- Will show successful tracking algorithm
- GUI will show both actual and expected data



Schedule, Tasks, & Milestones

| SENIOR DESIGN SCHEDULE | Week | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 |
|----------------------------|------|-----|-------------|-----------|-----------|-----------|-----------|----------|----------|-----|-----|
| Task | | | | | | | | | | | |
| PROPOSAL | | ALL | | | | | | | | | |
| PROJECT SUMMARY | | ALL | | | | | | | | | |
| GUI DESIGN | | | ALL (GUI) | | | | | | | | |
| ORDER 2nd MATRIX | | | HARRY | | | | | | | | |
| Design Review Presentation | | | | | ALL | ALL | | | | | |
| Update Project Summary | | | | | ALL | ALL | | | | | |
| Microphone Test | | | AJ | | | | | | | | |
| Far-Field Test | | | AJ + SIDONG | | | | | | | | |
| Decide on Plan A or B | | | AJ + SIDONG | | | | | | | | |
| Build GUI (2D PLANE) | | | Daniel | GUI(TBD) | GUI(TBD) | GUI(TBD) | | | | | |
| Build GUI (Display Data) | | | Tiffany | GUI(TBD) | GUI(TBD) | GUI(TBD) | | | | | |
| Build GUI (QoL Features) | | | Andrew | GUI(TBD) | GUI(TBD) | GUI(TBD) | | | | | |
| Test GUI | | | | | | | GUI(TBD) | GUI(TBD) | | | |
| SINGLE SOURCE TEST | | | | AJ+SIDONG | AJ+SIDONG | | | | | | |
| MULTI SOURCE TEST | | | | | | AJ+SIDONG | AJ+SIDONG | | | | |
| TRACKING | | | | | AJ+SIDONG | AJ+SIDONG | AJ+SIDONG | | | | |
| INTERFACE GUI WITH ALGO | | | | | | | | GUI(TBD) | GUI(TBD) | | |
| CAPSTONE DESIGN EXPO | | | | | | | | ALL | ALL | ALL | ALL |
| FINAL DEMO | | | | | | | | ALL | ALL | ALL | ALL |
| FINAL REPORT | | | | | | | | ALL | ALL | ALL | ALL |
| Update Project Summary | | | | | | | | ALL | ALL | ALL | ALL |





Cost Analysis

- Requested budget for another Matrix Voice is \$90
- Collectively, about 20-25 hours per week for labor and research
 - 12 to 15 hours for research
 - 4 to 6 hours for algorithm development
 - 4 hours for GUI research and development
- Cost of labor is about \$800 to \$1,000
 - Used a laxed cost of \$40 an hour



Current Status

- Algorithm has been translated from MATLAB to Python
 - Algorithm can be run repeatedly from executable
 - Angle estimation has high accuracy
 - RSS model training is
 - Implement time difference followed by angle calculation.
 - RSS model will be established.
- GUI team is focused on adding features and interfacing with Algo
 - Button Functionality has been established
 - Graphing predicted vs real source location is next project goal

Leadership Roles

1. Tiffany Ho:

- \circ Group leader
- o Documentation Coordinator

2. Daniel Scarborough:

 \circ Webmaster

3. Ajeetpal Dhillon:

- o Documentation Coordinator
- Software/Algorithms Lead

4. Harry Nguyen:

• Financial Manager

5. Sidong Guo:

Software/Algorithms Lead

6. Andrew Dulaney:

 \circ Hardware Lead

